# JEFFREY NANOFLUID FLUID FLOW INDUCED DUE TO THE IMPULSIVE MOVEMENT OF RIGA PLATE

## STRUJANJE JEFFREY NANOFLUIDA INDUKOVANOG IMPULSNIM KRETANJEM RIGA PLOČE

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Adresa autora / Author's address:

<sup>1)</sup> School of Technology, Pandit Deendayal Energy University, Gandhinagar, India

### Keywords

- convective boundary condition
- Jeffrey nanofluid
- spectral quasilinearization method
- · Riga plate, impulsive movement
- · activation energy

#### Abstract

Unsteady flow, induced by an impulsive movement of boundary, of Jeffrey nanofluid over surface having the ability to bring about electromagnetic hydrodynamic behaviour is studied. Integrated effects of magnetic field, modified Lorentz force, viscous dissipation, thermophoresis, Brownian motion, activation energy and convective boundary conditions are considered in the present flow analysis. Mathematical replica of the flow system in terms of system of nonlinear and coupled partial differential equations is solved using spectral quasilinearization recipe. Solutions obtained by this method are substituted in the original system of equations and a very good outcome is achieved. A detailed study on the effects of some selected flow parameter is performed by replicating the solutions in graphical form. Expressions of Nusselt and Sherwood number are presented.

### INTRODUCTION

Nanofluid takes a very crucial position in the field of science and engineering owing to its enhanced thermal conductivity. Some of fascinating applications of nanofluid include innovating new generation of cooling technology, solar thermal systems, biomedical science, heat exchangers. thermal energy transport, metal working processes, textile industry and food processing, etc. Additionally, the effects of heat transfer mediated by nanofluids have great effects across the research and industrial sectors. The impact of nanofluids has been enormous, in the field of industrial applications such as spanning discs, plates, parallel plates, cylinders, parallel discs, stretching sheets, stretching discs, cones, or channels in both rotating and non-rotating environments. Gupta et al. /1/ remarked on interplay of magnetic fields, mixed convection, radiation, and chemical reactions within the context of non-Newtonian nanofluid dynamics. Shafiq et al. /2/ presented the fascinating realm of Casson Marangonidriven forced convection in nanofluids, near an infinite disk under inclined magnetic field. Rasool and Zhang /3/ ventured into the Cattaneo-Christov models, shedding light on the heat and mass diffusion in nanofluids near nonlinear stretching <sup>2)</sup> School of Computer Science and Applied Mathematics, Faculty of Science, University of the Witwatersrand, Johannesburg, Gauteng, South Africa

<sup>3)</sup> Institute of Management, Nirma University, Ahmedabad, Gujarat, India \*email: <u>mumukshutrivedi@nirmauni.ac.in</u>

### Ključne reči

- granični uslov konvekcije
- Jeffrey nanofluid
- metoda spektralne kvazilinearizacije
- Riga ploča, impulsno kretanje
- energija aktivacije

#### Izvod

U radu se proučava nestacionarno strujanje Jeffrey nanofluida preko površine koja izaziva elektromagnetno hidrodinamičko ponašanje, gde je strujanje indukovano impulsnim kretanjem granične površine. U analizi strujanja razmatraju se integrisani uticaji magnetnog polja, modifikovane Lorencove sile, viskoznog trenja, termoforeze, Braunovog kretanja, energije aktivacije i graničnih uslova konvekcije. Matematički model sistema strujanja opisan sistemom nelinearnih i spregnutih parcijalnih diferencijalnih jednačina se rešava primenom metode spektralne kvazilinearizacije. Smenom dobijenih rešenja u početni sistem jednačina postiže se veoma dobar ishod. Rešenja dobijena grafički doprinose detaljnom proučavanju uticaja pojedinih izabranih parametara strujanja. Dati su i izrazi za Nuseltov i Šervudov broj.

sheet coursing through non-Darcian porous media. Rasool et al. /4/ shredded some light on the mechanics behind forced convection flow in second-grade nanofluids, considering the Lorentz force and Marangoni effects. Contribution by Lund et al. /5/ explored the stability of Casson nanofluid flows at an exponentially shrinking surface in Darcy Forchheimer porous media. Nayak et al. /6/ studied the multifaceted effects of momentum, thermal, and solutal slips at electromagnetic sheets experiencing stagnation flows of Walters' B nanofluids. This analysis incorporates the Cattaneo-Christov flux concept on heat and mass diffusion. The effects of an elevated magnetic field, non-uniform heat source/sink and chemical reaction on viscous dissipative and radiative unsteady flow of a Williamson nanofluid across a vertical extending porous surface are well demonstrated in /7/. The characteristics of heat transfer on viscous dissipative flow of Jeffrey nanofluid, induced due to impulsive movement of plate with the impact of activation energy was reported by Trivedi et al. /8/. Casson nanofluid comprising the combined effects of Hall current, activation energy, externally heat source/sink and radiation was simulated numerically by Kumar et al. /9/.

In addition to the aforementioned geometrical constructions, the Riga plate or electromagnetic actuator, which is an outcome of pioneer work by Gailitis and Lielausis /10/, is a tool that can generate Lorentz force along a boundary wall. A magnetic and electric field produced by the Riga plate, made up of alternate positioning of electrodes and magnets in span-wise aligned arrays, increase the Lorentz force in the fluid flow direction. Riga plate counterbalances fluid flow close to boundary layer. Electromagnetic force, in addition to wall motion and suction, controls fluid flow. Applying an electrical field is beneficial for effective flow control because a magnetic field does not generate enough currents when weakly conducting fluids are involved. Riga plate minimizes boundary layer separation, skin friction, and pressure drag on submarines. Magnetic force-driven flows across the Riga plate are important in a variety of industrial and engineering operations. Hayat et al. /11/ studied the properties of heat transfer of nanofluid flow induced by the convectively heated Riga surface taking into account heat generation/absorption effects. Rasool et al. /12/, conducted an analysis on the behaviour of second grade nanofluid flows at a vertically heated Riga plate. Shamshuddin et al. /13/ explored the influence of absorption and Joule heating on magnetohydrodynamic (MHD) flow between Riga plates, considering the Cattaneo-Christov heat flux. Hakeem et al. /14/ examined the influence of nonlinear thermal radiation on 3-dimensional flow of nanofluid consisting base fluid as water and sodium alginate and nanoparticle as aluminium oxide and magnetite, adjacent to a Riga plate. Ragupathi et al. /15/ examined the probability of achieving distinct findings by comparing FeO<sub>4</sub>/Al<sub>2</sub>O<sub>3</sub> nanoparticles with H<sub>2</sub>O/ NaC<sub>6</sub>H<sub>9</sub>O<sub>7</sub> as base nanofluids over the Riga plate with irregular heat source/sink effects. Iqbal et al. /16/ studied the effects of viscous dissipation, thermal radiation, and melting heat on stagnation point flow across the Riga surface. This study shows that melting heat transfer has direct relation with radiation parameter and inverse relation with temperature distribution. Rida et al. /17/ investigated the process of heat transfer in nanofluid flow past a vertical convectively heated Riga plate under zero normal wall mass flux condition. Papers /18-24/ explore various aspects of nanofluid flow over Riga surface. Nasir et al. /25/ investigated the characteristics of two base fluids, namely, H<sub>2</sub>O and C<sub>2</sub>H<sub>6</sub>O<sub>2</sub> and TiO<sub>2</sub> nanoparticle in unsteady electromagnetohydrodynamic nanofluid flow over Riga plate with radiation. It was revealed that nanofluid consisting of C<sub>2</sub>H<sub>6</sub>O<sub>2</sub> as base fluid possesses improved heat transfer than nanofluid with H<sub>2</sub>O as base fluid. Alhowaity et al. /26/ analysed the consequences of activation energy and heat generation on radiative flow of a nanofluid at convected vertical Riga plate employing zero mass flux and convectively heated surface. Algehyne et al. /27/ investigated effects of magnetic field, microorganism, activation energy and heat source/sink on flow of hybrid MgO-Ag water nanoliquid at Riga plate allowing slip at boundary surface. Aamir et al. /28/ discussed the flow properties of an Al<sub>2</sub>O<sub>3</sub>-Cu water hybrid nanofluid via a Riga plate integrating the factors like heat flux, suction, viscous dissipation, entropy generation, convective and slippage condition at the bounding surface. Riaz et al. /29/ reported an analysis on heat and mass transfer, using Cattaneo-Christov model, of ZnO-SAE50 nanolubricant in a Darcy Forchheimer medium past a Riga plate. Ansari et. al. /30/ made an effort to describe the Jeffrey nanofluid flow phenomenon on a Riga plate by incorporating the effects of inconsistent heat source/sink and viscous dissipation. Ramanjini et al. /31/ examined the two-dimensional time dependent boundary layer mixed convective and radiative horizontally stretched flow of a Williamson nanofluid over a Riga plate.

A widespread literature survey reveals that a study pertaining to unsteady Jeffrey (rate type) nanofluid flow, generated by impulsive movement of a Riga surface with convective conditions doesn't exist. This work explores the unsteady flow of Jeffery nanofluid flow over surface that can exhibit electromagnetic hydrodynamic behaviour when the boundary is moved impulsively. The combined effects of a magnetic field, modified Lorentz force, viscous dissipations, thermophoresis, Brownian motion, activation energy and convective boundary conditions are taken into consideration in the analysis of heat transfer. The PDEs used to model this problem were numerically solved using the spectral quasilinearization technique. Mathematica® and MAT-LAB® were used to generate approximate solutions. Convergence and accuracy of numerical scheme were substantiated by evaluating the solution error and residual error, in respect. These assessments show a satisfactory outcome. The approximate results are displayed in graphical form to examine the insight of flow, temperature, and nanoparticle concentration pattern.

### MATHEMATICAL FORMULATION OF THE PROBLEM

An unsteady flow across an electromagnetic surface, Riga surface, considering the surface along  $\eta$  direction where  $\xi$ direction is considered normal to the surface. The unsteady nature of the flow and Jeffrey nanofluid is considered. The following points are considered while modelling the flow system.

- 1. Flow properties are dependent only on  $\xi$  direction and time.
- 2.  $\hat{\phi}_{1\infty}$  and  $\hat{\phi}_{2\infty}$  are fluid temperature and nanoparticle concentration outside the boundary layer region.
- 3. Magnetic field of constant strength is applied in the  $\xi$  direction.
- 4. Induced magnetic field is neglected.
- 5. Arrhenius activation energy is considered.
- 6. Flow is induced by impulsive movement of the electromagnetic surface.
  - Figure 1 is the pictorial representation of the flow system.



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Figure 1. Schematic diagram of Jeffrey nanofluid over Riga plate.

Under the above mentioned points, Eqs.(1)-(3) are the mathematical representation of this problem.

$$\partial_{\hat{t}}\hat{v}_{1} = \nu b^{-1} (1 + \lambda_{2}\partial_{\hat{t}}) \partial_{\xi\xi} \hat{v}_{1} - \sigma \rho^{-1} B^{2} \hat{v}_{1} + \frac{\pi J_{0} M_{0}}{8\rho} e^{\pi a^{-1}\xi}, \quad (1)$$
  
$$\partial_{\hat{t}}\hat{\phi}_{1} = \alpha \partial_{\xi\xi} \hat{\phi}_{1} + \tau \Big[ D_{B} \partial_{\xi} \hat{\phi}_{2} \partial_{\xi} \hat{\phi}_{1} + D_{\hat{\phi}_{1}} (\hat{\phi}_{1\infty})^{-1} (\partial_{\xi} \hat{\phi}_{1})^{2} \Big] +$$

$$+\mu(\rho c_{p}b)^{-1} \Big[ (\partial_{\xi}\hat{v}_{1})^{2} + \lambda_{2}\partial_{\xi}\hat{v}_{1}\partial_{\hat{t}\xi}\hat{v}_{1} \Big], \qquad (2)$$

$$\partial_{\hat{t}}\hat{\phi}_{2} = D_{B}\partial_{\xi\xi}\hat{\phi}_{2} - k_{r}^{2}(\hat{\phi}_{1})^{n}(\hat{\phi}_{1\infty})^{-n}e^{-E_{a}(k\hat{\phi}_{1})^{-1}}(\hat{\phi}_{2} - \hat{\phi}_{2\infty}) +$$

$$+D_{\hat{\phi}_{1}}(\hat{\phi}_{1\infty})^{-1}\partial_{\xi\xi}\hat{\phi}_{1}, \qquad (3)$$

where: parameters *a*, *B*,  $\sigma$ , *j*<sub>0</sub>, *M*<sub>0</sub> are respectively, width of magnets between electrodes, applied magnetic field strength, electrical conductivity, current density in electrode, and the magnetization of magnets mounted on the surface of Riga plate. Parameters  $\hat{v}_1, \hat{\phi}_1, \hat{\phi}_2, \hat{\phi}_{1\infty}, \hat{\phi}_{2\infty}, \lambda_1, \lambda_2, (\rho c)_f, D_B, , k_r^2, E_a, D_{\hat{\phi}_1}$ , and  $\tau$  are, respectively, fluid velocity in  $\eta$ -direction, fluid temperature, nanoparticle concentration, ambient temperature, ambient concentration, ratio of relaxation to retardation time, relaxation time, kinematic viscosity, density of base fluid, specific heat at constant pressure, effective heat capacity of the nanoparticle material, heat capacity of the fluid, Brownian diffusion coefficient, thermophoresis diffusion coefficient, chemical reaction rate constant, activation

energy, and a parameter defined by ratio  $(\rho c)_p / (\rho c)_f$ . The term  $k_r^2 (\hat{\phi}_1)^n (\hat{\phi}_{1\infty})^{-n} e^{-E_a (k\hat{\phi}_1)^{-1}} (\hat{\phi}_2 - \hat{\phi}_{2\infty})$  symbolizes transfigured Arrhenius function, where *n* is a constant exponent. Also  $b = 1 + \lambda_1$ . The pressure gradient and external forces are neglected in momentum equation.

Boundary conditions:

$$\hat{t} = 0; \quad \forall \xi; \; \hat{v}_1 = 0, \; \hat{\phi}_1 = 0, \; \hat{\phi}_2 = 0,$$
 (4)  

$$\begin{bmatrix} \text{st} & \xi = 0; \; \hat{v}_1 = v; \; v \in k \geq \hat{\phi}_1 = h(\hat{\phi}_2 = \hat{\phi}_1) \end{bmatrix}$$

$$\hat{t} > 0: \begin{cases} \text{at} \quad \xi = 0; \quad v_1 = v_0; \quad -\kappa \partial_{\xi} \phi_1 = h_1(\phi_{1w} - \phi_1) \\ -D_B \partial_{\xi} \hat{\phi}_2 = h_2(\hat{\phi}_{2w} - \hat{\phi}_2) \\ \text{as} \quad \xi \to \infty; \quad v_1 \to 0; \quad \hat{\phi}_1 \to 0; \quad \hat{\phi}_2 \to 0 \end{cases}$$
(5)

where:  $\hat{v}_1$  denotes velocity in  $\eta$  direction;  $h_1$  is the surface heat transfer coefficient;  $h_2$  is wall mass transfer coefficient. Equations (1)-(3) can be transformed into equivalent partial differential equations using the technique of similarity solutions. We introduce the following dimensionless variables:

 $v = \hat{v}_{1} / v_{0}, \quad y = \xi / \xi_{0}, \quad \xi_{0} = v / v_{0}, \quad t = \hat{t} / \hat{t}_{0}, \quad \hat{t}_{0} = v / v_{0}^{2}, \\ \phi_{1} = (\hat{\phi}_{1} - \hat{\phi}_{1\infty}) / (\hat{\phi}_{1w} - \hat{\phi}_{1\infty}), \quad \phi_{2} = (\hat{\phi}_{2} - \hat{\phi}_{2\infty}) / (\hat{\phi}_{2w} - \hat{\phi}_{2\infty}).$ (6) Using Eq.(6) in Eqs.(1)-(3), the non-dimensional system is:  $\partial_{yy}v + \lambda (\partial_{t}\partial_{yy}v) - b\partial_{t}v + bQe^{-\beta y} - bMv = 0,$ (7)

$$-\partial_t \phi_1 + N_{\phi_1} (\partial_y \phi_1)^2 + \operatorname{Ec} b^{-1} [(\partial_y v)^2 + \lambda \partial_y v \partial_{ty} v] + + (\operatorname{Pr})^{-1} \partial_{yy} \phi_1 + N_b \partial_y \phi_2 \partial_y \phi_1 = 0, \qquad (8)$$

$$\partial_{yy}\phi_{2} - \operatorname{Le}\partial_{t}\phi_{2} - \operatorname{Le}k(\phi_{1}\delta + 1)^{n}e^{-E(\phi_{1}\delta + 1)^{-1}}\phi_{2} + N_{\phi}(N_{b})^{-1}\partial_{yy}\phi_{1} = 0, \qquad (9)$$

and the transformed conditions are

at t=0 and  $\forall y>0$ : v(y,0)=0,  $\phi_1(y,0)=0$ ,  $\phi_2(y,0)=0$ , at y=0 and  $\forall t>0$ :  $\partial_y \phi_1 = -\Gamma_1(1-\phi_1)$ ,  $\partial_y \phi_2 = -\Gamma_2(1-\phi_2)$ , as  $y \to \infty$  and  $\forall t>0$ :  $v(\infty,t) \to 0$ ;  $\phi_1 \to 0$ ;  $\phi_2 \to 0$ , (10) where:

$$\begin{split} M &= \sigma B^2 / \rho v, \ \lambda = \lambda_2 v_0^2 / v, \ Q = \pi j_0 M_0 / 8 \rho v, \ \beta = \pi v / a v_0, \\ \Pr &= v / \alpha, \ \delta = (\phi_{1w} - \phi_{1\infty}) / \phi_{1\infty}, \ N_b = \tau D_B (\phi_{2w} - \phi_{2\infty}) / v, \\ N_{\phi_1} &= \tau D_{\phi_1} (\phi_{1w} - \phi_{1\infty}) / v \phi_{1\infty}, \ k = k_r^2 v / v_0^2, \ \text{Le} = v / D_B, \\ \text{Ec} &= v_0^2 / v (\phi_{1s} - \phi_{1\infty}), \ \alpha = k / (\rho c)_f, \ E = E_a / k \phi_{1\infty}, \end{split}$$

where: M, Q,  $\beta$ , Pr,  $N_b$ ,  $N_{\phi 1}$ , Le, Ec, E, and  $\Gamma_i$  (i = 1, 2, 3) are respectively, magnetic parameter, modified Hartmann number, dimensionless constant, Prandtl number, Brownian motion parameter, thermophoresis parameter, Lewis number, Eckert number, activation energy parameter and Biot numbers.

Nusselt number Nu<sub>x</sub> and Sherwood number Sh<sub>x</sub>, are presented as: Nu<sub>x</sub> =  $-\partial_y \phi_1 \Big|_{y=0}$ , Sh<sub>x</sub> =  $-\partial_y \phi_2 \Big|_{y=0} = 0$ .

## SOLUTION TECHNIQUE

The Eqs. (7) to (9) are nonlinear and coupled, making it generally hard to find an analytical solution. Here, we will go through SQLM method and use it to arrive at a numerical solution for systems Eqs.(7)-(9) under boundary conditions Eq.(10). In order to force the system of equations to be solved, it is initially figured that the system consists of separate equations for v,  $\phi_1$ , and  $\phi_2$ . The approximate solutions of each function and their derivatives at successive iteration levels (i.e., at  $(r + 1)^{\text{th}}$  and  $r^{\text{th}}$  level, r is iteration level) differ slightly, hence a quasilinearization technique employing Taylor series expansion is used to linearize the resolved equations. By using the Chebyshev spectral collocation method, the linear resolved system of equations is solved. Nonlinear terms in the system of Eqs. (7)-(9) are  $\partial_{\nu}\phi_1\partial_{\nu}\phi_2$ ,  $(\partial_{\nu}\phi_1)^2$ ,  $(\partial_{\nu}\nu)^2$ ,  $\partial_{\nu}\nu\partial_{t\nu}^2\nu$ ,  $(1+\phi_1\delta)^n$ , and  $(1+\phi_1\delta)^{-1}$ ,  $\delta$ is the temperature difference parameter.

First, we convert Eqs.(7)-(9) into quasilinear form as:

$$v_{r+1}'' + [a_1]v_{r+1} = -\lambda \partial_t v_{r+1}'' + b\partial_t v_{r+1},$$
  

$$[b_1]v_{r+1}' + \frac{1}{\Pr} \phi_{1r+1}'' + [b_2]\phi_{1r+1}' + [b_3]\phi_{2r+1}' =$$
  

$$= [b_4]\partial_t w_{r+1}' + \partial_t \phi_{1r+1} + b_5,$$
  

$$N_{\phi_1} (N_b)^{-1} \phi_{1r+1}'' + [c_1]\phi_{1r+1} + \phi_{2r+1}'' + [c_2]\phi_{2r+1} =$$
  

$$= \operatorname{Le} \partial_t \phi_{2r+1} + c_3,$$
(11)

where the iteration levels for the current and previous iterations are indicated by subscripts r + 1 and r and

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$$a_{1} = -bM, \ b_{1} = 2Ecb^{-1}v'_{r} + \lambda Ecb^{-1}\partial_{t}v'_{r}, b_{2} = N_{b}\phi'_{2r} + 2N_{\phi_{1}}\phi'_{1r}, \ b_{3} = N_{b}\phi'_{1r}, \ b_{4} = -\lambda Ecb^{-1}v'_{r}, b_{5} = N_{b}\phi'_{1r}\phi'_{2r} + N_{\phi_{1}}\phi'_{1r}^{2} + Ecb^{-1}v'_{r}^{2} + \lambda Ecb^{-1}v'_{r}\partial_{t}v'_{r}, c_{1} = -LeK\phi_{2r}\delta exp(-E(1+\phi_{1r}\delta)^{-1})[n(\phi_{1r}\delta+1)^{n-1} + E(\phi_{1r}\delta+1)^{n-2}], c_{2} = -LeK(\phi_{1r}\delta+1)^{n} exp(-E(1+\phi_{1r}\delta)^{-1}), c_{3} = -LeKexp(-E(1+\phi_{1r}\delta)^{-1})\{(\phi_{1r}\delta+1)^{n} + \phi_{2r}\phi_{1r}\delta \times \\ \times [n(\phi_{1r}\delta+1)^{n-1} + E(\phi_{1r}\delta+1)^{n-2}]\}.$$
(12)

where: *K* is a chemical reaction parameter.

Chebyshev collocation spectral method is used to solve the system Eqs.(13)-(15), for this the space and the time domain is transformed to [-1, 1] by using linear transformation. Bivariate Lagrange interpolation polynomials are used to govern approximate solution, which is defined as

$$Y(y,t) \approx \sum_{i=0}^{M_y} \sum_{j=0}^{M_t} Y(y_i,t_j) L_i(y) L_j(t), \quad F = (v,\phi_1,\phi_2),$$
(13)

which interpolates unknowns: fluid velocity, temperature and concentration at Gauss-Lobatto collocation points, defined as

$$y_i = \cos\left(\frac{\pi i}{M_y}\right), t_j = \cos\left(\frac{\pi j}{M_t}\right), i = 0, 1, \dots, M_y, j = 0, 1, \dots, M_t$$

Chebyshev differentiation matrices *D*, *d* with respect to *y* (space variable) and *t* (time variable) of order  $(M_y + 1) \times (M_y + 1)$  and  $(M_t + 1) \times (M_t + 1)$ , respectively, are taken as

$$\frac{\partial^m \mathbf{Y}}{\partial y^m}\Big|_{(y_k,t_i)} = \mathbf{D}^m \mathbf{Y}_i, \quad m = 1, 2, 3, \quad \frac{\partial \mathbf{Y}}{\partial t}\Big|_{(y_k,t_i)} = \sum_{j=0}^{M_y} \mathbf{d}_{ij} \mathbf{Y}_j \quad (14)$$

Thus  $\mathbf{Y}_i$  represents  $\mathbf{Y}_i = [Y_i(y_0), Y_i(y_1), \dots, Y_i(y_{M_y})]^T$ . (15)

The system Eq.(11) which is now linearized, is divided into smaller disjoint intervals  $\rho_s = [t_{s-1}, t_s]$ , s = 1, 2, ..., T, where  $T \in \rho$ ,  $\rho = [0, T]$  by breaking up the time interval t. The fundamental principle of the multi-domain method is highlighted by this splitting process. The approach is used to find solutions to the problem inside the first subinterval by starting with an initial solution that fulfils the boundary conditions of the system of partial differential equations. Once the system of equations has been solved in all subintervals, the resulting solutions are used as initial solutions in the following sub-interval. A continuity condition can be used to express this as

$$Y^{(\mathcal{E})}(y, t_{\mathcal{E}-1}) = F^{(\mathcal{E}-1)}(y, t_{\mathcal{E}-1}).$$
(16)

The system Eq.(11) assumes the form after the multidomain approach is used as

$$v_{r+1}^{\prime\prime\varepsilon} + (a_1)v_{r+1}^{(\varepsilon)} = -\lambda\partial_t v_{r+1}^{\prime\prime\varepsilon} + b\partial_t v_{r+1}^{(\varepsilon)},$$

$$[b_1^{(\varepsilon)}]v_{r+1}^{\prime\prime\varepsilon} + \frac{1}{\Pr}\phi_{1r+1}^{\prime\prime\varepsilon} + [b_2^{(\varepsilon)}]\phi_{1r+1}^{\prime\prime\varepsilon} + [b_3^{(\varepsilon)}]\phi_{2r+1}^{\prime\varepsilon} =$$

$$= [b_4^{(\varepsilon)}]\partial_t v_{r+1}^{\prime(\varepsilon)} + \partial_t \phi_{1r+1}^{(\varepsilon)} + b_5^{(\varepsilon)},$$

$$N_{\phi_1}(N_b)^{-1}\phi_{1r+1}^{\prime\prime\varepsilon} + [c_1^{(\varepsilon)}]\phi_{1r+1}^{(\varepsilon)} + \phi_{2r+1}^{\prime\prime\varepsilon} + [c_2^{(\varepsilon)}]\phi_{2r+1}^{(\varepsilon)} =$$

$$= \operatorname{Le}\partial_t \phi_{2r+1}^{(\varepsilon)} + c_3^{(\varepsilon)}.$$
(17)

By applying the Chebyshev spectral method on the linearized system of Eqs.(17), we obtain

$$\mathbf{A}_{11,i}^{(\varepsilon)}(\mathbf{v})_{r+1,i}^{(\varepsilon)} + \mathbf{A}_{12,i}^{(\varepsilon)}(\mathbf{\Phi}_{1})_{r+1,i}^{(\varepsilon)} + \mathbf{A}_{13,i}^{(\varepsilon)}(\mathbf{\Phi}_{2})_{r+1,i}^{(\varepsilon)} + \\
+ \lambda \sum_{j=0}^{M_{y}} \mathbf{d}_{i,j} \mathbf{D}^{2} \mathbf{v}_{r+1,j}^{(\varepsilon)} - b \sum_{j=0}^{M_{y}} \mathbf{d}_{i,j} \mathbf{v}_{r+1,j}^{(\varepsilon)} = \mathbf{R}_{1,i}^{(\varepsilon)}, \quad (18)$$

$$\mathbf{A}_{21,i}^{(\varepsilon)}(\mathbf{v})_{r+1,i}^{(\varepsilon)} + \mathbf{A}_{22,i}^{(\varepsilon)}(\mathbf{\Phi}_{1})_{r+1,i}^{(\varepsilon)} + \mathbf{A}_{23,i}^{(\varepsilon)}(\mathbf{\Phi}_{2})_{r+1,i}^{(\varepsilon)} - [\mathbf{b}_{4,i}^{(\varepsilon)}] \times$$

$$\times \sum_{j=0}^{M_{y}} \mathbf{d}_{i,j} \mathbf{D} \mathbf{v}_{r+1,j}^{(\varepsilon)} - \sum_{j=0}^{M_{y}} \mathbf{d}_{i,j} (\mathbf{\Phi}_{1})_{r+1,j}^{(\varepsilon)} = \mathbf{R}_{2,i}^{(\varepsilon)}, \quad (19)$$

where: 
$$\mathbf{A}_{11,i}^{(\varepsilon)} = \mathbf{D}^2 + (a_1)\mathbf{I}, \quad \mathbf{A}_{12,i}^{(\varepsilon)} = \mathbf{A}_{13,i}^{(\varepsilon)} = 0, \quad \mathbf{A}_{21,i}^{(\varepsilon)} = [\mathbf{b}_1^{(\varepsilon)}]\mathbf{D},$$
  
 $\mathbf{A}_{22,i}^{(\varepsilon)} = \frac{1}{\Pr}\mathbf{D}^2 + [\mathbf{b}_2^{(\varepsilon)}]\mathbf{D}, \quad \mathbf{A}_{13,i}^{(\varepsilon)} = [\mathbf{b}_3^{(\varepsilon)}]\mathbf{D}, \quad \mathbf{A}_{31,i}^{(\varepsilon)} = \mathbf{0},$   
 $\mathbf{A}_{32,i}^{(\varepsilon)} = N_{\phi_1}(N_b)^{-1}\mathbf{D}^2 + [c_1^{(\varepsilon)}], \quad \mathbf{A}_{33,i}^{(\varepsilon)} = \mathbf{D}^2 + [\mathbf{c}_2^{(\varepsilon)}]$   
and **I** is an identity matrix of size  $(M_y + 1) \times (M_y + 1).$ 

#### CONVERGENCE AND ACCURACY

This section describes the accuracy of convergent solutions obtained with SQLM as well as the convergence of solutions. Figures 2-10 demonstrate the accuracy of the numerical scheme and convergence for  $N_b = 0.1$ ,  $N_t = 0.1$ , Le = 10,  $\delta = 1$ , E = 0.05, Pr = 12, M = 3, Ec = 0.2, n = 1, K = 1,  $\lambda = 0.1$ ,  $\lambda_1 = 0.1$ , and Q = 1. In *y* (space) direction 80 gridpoints in *t* (time) are used. The results of grid-independent test show that these are capable of producing accurate solutions.

#### Solution error analysis

When Q = 1,  $N_b = 0.1$ ,  $N_t = 0.1$ , Le = 10,  $\delta = 1$ , E = 0.05, Pr = 12, M = 3, Ec = 0.2, n = 1, K = 1,  $\lambda = 0.1$ , and  $\lambda_1 = 0.1$ , by calculating the error derived from the solutions of two successive iterations and taking the infinity norm, convergence of the SQLM test is accomplished,

$$\|v\|_{\infty} = \max_{0 \le i \le M_{y}} \|v_{r+1,i} - v_{r,i}\|_{\infty}, \qquad (21)$$

When the error between successive solutions becomes consistent to a defined number of significant digits, indicating that additional increases in the number of iterations have no effect on the corresponding solutions, the approximate solution achieved using the SQLM is said to have converged. Figures 2-4 display solution errors of the system of PDEs. The solution error shows a monotonic decline as the number of iterations rises, demonstrating the convergence of the solution approach. It can be seen that the error reduces to  $10^{-14}$  just after the few iterations and remains consistent for  $\nu$  while it takes almost 6 iterations for convergence to occur for  $\phi_1$  to  $10^{-14}$  and  $\phi_2$  to  $10^{-13}$ . This solution error analysis confirms a quick convergence of solution method in a lower number of iterations,





### **RESULTS AND DISCUSSION**

This section emphasizes to assess the behaviour of physical parameters on fluid velocity v, temperature  $\phi_1$ , and nanoparticle concentration  $\phi_2$  in the boundary layer region. The following values of parameters, i.e., M = 3, Pr = 12,  $\delta = 1$ ,  $N_b = 0.1$ ,  $N_t = 0.1$ , E = 0.05,  $\lambda = 0.1$ ,  $\lambda_1 = 0.1$ , Le = 10, n = 1, k = 1, Ec = 0.2,  $\beta = 0.5$ ,  $\Gamma_1 = 2$ ,  $\Gamma_2 = 1$ , and Q = 1 are utilised to generate the graphs.

An impact of parameter  $\beta$  on the velocity profile near the boundary layer region is picturised in Fig. 11. An upsurge in  $\beta$  reveals a decline in velocity profile.



Figures 12-15 witness the influence of Biot numbers on the temperature and concentration profiles. Improvement in convective heat and mass transfer coefficient shows an elevation in fluid temperature as well as nanoparticle concentration profiles near the bounding surface. Fluid temperature and nanoparticle concentration drop uniformly along  $\eta$ to adhere the free stream values. Nanoparticle concentration grows near the wall on account of sedimentation. This happens because of the convectively heated boundary surface.

Figures 16-18 show the response of modified Hartmann number on fluid velocity, temperature profile, and nanoparticle concentration. Since Riga plate produces electromagnetic waves and this electromagnetic force acts along the fluid motion, this helps to enhance fluid velocity and concentration profiles. This fact is revealed from the Figs. 16 and 18. Modified Hartman number exerts a diminishing influence in fluid temperature, i.e., a boost in heat transfer (Fig. 17).





Activation energy signifies a small amount of energy that causes a transformation or chemical reaction, augments nanoparticle concentration (Fig. 19). The potential for reaction rate is increased by activation energy, which also increases the nanoparticle concentration in the boundary layer region.



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STRUCTURAL INTEGRITY AND LIFE Vol. 25, Special Issue A 2025, pp. S93–S100 Response of time on fluid velocity, temperature, and concentration is summarised in Figs. 20-22. It is delineated from Figs. 20-22 that momentum, thermal, and concentration boundary layer develops with time. The time has an enhancing nature on fluid velocity, temperature, and nanoparticle concentration. The values of heat transfer coefficient (Nusselt number) and mass transfer coefficient (Sherwood number) are depicted in Table 1 for varying the modified Lorentz force, Prandtl number, Eckert number, and thermal and solutal Biot number.



Table 1. Impact of Q, Pr, Ec,  $\Gamma_1$ , and  $\Gamma_2$  on Nu<sub>x</sub> (Nusselt number) and Sh<sub>x</sub> (Sherwood number).

Q	Pr	Ec	$\Gamma_1$	$\Gamma_2$	Nu <sub>x</sub>	$\mathbf{Sh}_x$
1	12	0.2	2	1	0.786042	0.786767
2					0.866916	0.766515
3					0.966547	0.749551
	2				0.595822	0.794169
	4				0.692376	0.788361
	6				0.793691	0.786285
		0			1.106348	0.713762
		0.1			0.946944	0.750804
		0.2			0.786042	0.786767
			1		0.573107	0.870261
			2		0.786042	0.786767
			3		0.898032	0.782075
				1	0.786042	0.786767
				2	0.756241	1.331982
				3	0.733173	1.728639

### CONCLUSION

Transient Jeffery nanofluid flow over a surface, capable of manifesting electromagnetic hydrodynamic behaviour is explored. Impulsive movement of the Riga plate is accounted. Heat transfers are simulated by incorporating the combined effects of a magnetic field, a modified Lorentz force, viscous dissipations, thermophoresis, Brownian motion, and convective boundary conditions. The spectral quasilinearization method is implemented to generate approximate solutions of partial differential equations representing the flow system. MATLAB® is used to run the code of numerical scheme. Impacts of selected parameters are studied. By assessing the solution and residual error norms, convergence of the method and accuracy of obtained solutions are substantiated. The solution error norms show a decline in the error until convergence takes place, verifying the convergence of the approach. Residual error norms indicate that the approximate solutions generated using the SQLM approach are accurate. The following key results are deduced from this study:

- $\beta$  has a decreasing influence on fluid velocity.
- Fluid temperature and nanoparticle concentration increase with the thermal Biot number.
- Temperature and concentration profiles intensify with an increase in the solutal Biot number.
- An inverse relation of the modified Hartmann number with the temperature profile is observed. Velocity and concentration profiles increase with an increment in the modified Hartmann number.
- The concentration profile improves with a rise in the Arrhenius activation energy parameter.
- With the increase in time, the fluid velocity, temperature, and concentration profiles augment.

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