# EVALUATION OF THERMAL ELASTIC-PLASTIC STRESSES IN TRANSVERSELY ISOTROPIC DISK MADE OF PIEZOELECTRIC MATERIAL WITH VARIABLE THICKNESS AND VARIABLE DENSITY SUBJECTED TO INTERNAL PRESSURE

# ODREĐIVANJE TERMIČKIH ELASTOPLASTIČNIH NAPONA U TRANSVERZALNO IZOTROPNOM DISKU OD PIEZOELEKTRIČNOG MATERIJALA PROMENLJIVE DEBLJINE I GUSTINE KOJI JE OPTEREĆEN UNUTRAŠNJIM PRITISKOM

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piezoelectric materials	<ul> <li>piezoelektrični materijali</li> </ul>
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### Abstract

Piezoelectric materials have several packages in engineering and scientific fields. Piezoelectricity is the characteristic of the material due to which the electrical subject is generated in them when mechanical load is applied. PZT4 and BaTiO<sub>3</sub> are examples of unnatural piezoelectric substances. In this paper the analytic solution is discussed of thermal stresses in a thin rotating transversely isotropic disk consisting of a piezoelectric with variable thickness and density. Seth's idea of transition is implemented to simplify the governing differential equation. The obtained results are presented graphically and quantitatively. On the idea of evaluation, it is far discovered that a disk made of piezoelectric material barium titanate  $(BaTiO_3)$  is better than a disk made of PZT4 (piezoceramic). Parameters obtained from this research can be used to design pressure sensors. radar antennae, and many other devices, machines, or structures in engineering applications.

# INTRODUCTION

Materials have played an essential position from the early records of mankind. These days piezoelectric substances additionally play an important position in numerous technological packages, which include dental implants and bone implants in scientific subjects and many more. In mid-18th century, Curie brothers verified the existence of the piezoelectric action in quartz, tourmaline, topaz, cane sugar, and Rochelle salt crystals. The first actual application of piezoelectric substances became an ultrasonic submarine detector with the aid of Pierre Langevin in 1917. Piezoelectric substances have splendid importance nowadays and these materials have numerous programmes in extraordinary science and engineering fields. Fuel efficiency of cars is more desirable by piezoelectric fuel injection, airbags are controlled by means of a piezoelectric acceleration sensor and an ultrasonic parking sensor helps in avoiding collisions. Piezo motors are used for MRI monitored microsurgery in hospitals.

# Izvod

Piezoelektrični materijali imaju više primena u inženjerskim i u naučnim oblastima. Piezoelektrični efekat je karakteristika materijala u kojem se stvara električni napon pod dejstvom mehaničkog opterećenja. PZT4 i BaTiO<sub>3</sub> su primeri veštačkih piezoelektričnih materijala. U radu je data diskusija o analitičkom rešenju termičkih napona kod tankog rotirajućeg transverzalno izotropnog diska, koji je sačinjen od piezoelektričnog materijala, promenljive debljine i gustine. Ideja Seta o prelaznim naponima je uvedena radi uprošćenja polazne diferencijalne jednačine. Dobijeni rezultati su predstavljeni grafički i kvantitativno. Shodno dobijenim vrednostima, pokazuje se da je disk od piezoelektričnog materijala, barijum titanata ( $BaTiO_3$ ), bolji u odnosu na disk od PZT4 (piezokeramike). Parametri određeni u ovom radu se mogu upotrebiti u projektovanju senzora pritiska, radarskih antena, i u mnogim drugim uređajima, mašinama, ili konstrukcijama u inženjerskoj primeni.

Nguyen et al. /1/ added an isogeometric Bézier FE method to perform static bending and brief analysis of piezoelectric (FGP) plates bolstered with the aid of graphene platelets (GPLs). Barati and others /2/ used the polished four-unknown plate technique to study loose vibration of piezoelectric FGM plates with porosities.

To describe the shifting rule of graded material residences of a piezoelectric FGM, a modified electricity-law model was presumptively used. Hamilton's principle-derived governing equations were resolved analytically in a way that satisfied various boundary scenarios. In their study of the free and under pressure vibration of smart FG metal foam plate constructions supported by graphene platelets (GPLs), Nguyen et al. /3/ demonstrated that the proposed method was suitable for modelling both thick and thin structures.

Zharfi et al. /4/ calculated the creep stresses in rotating FGM disc through applying generalised differential quadrature answer method of differential equations. Mathematical model is advanced to analyse regular state creep stresses and pressure in a variable thickness rotating FGM disc through the use of Tresca yield criterion by way of Khanna et al. /5/. An analytical solution for a polarised circular cylinder, fabricated from piezoelectric FGM was found by Dai et al. /6/, who concluded that FGM have a significant impact. Jafari-Fesharaki et. al. /7/ discussed the analytical solution of a thick, spherical, piezoelectric FGM cylinder subjected to heat and mechanical loads as well as electrical issues. They validated their analytical approach with the aid of solving unique examples by means of this approach. Akbarzadeh et al. /8/ applied the Fourier-Laplace method, it was possible to compute the dynamic response of a functionally graded rectangular plate being subjected to a thermomechanical force. All of the above-cited authors implemented classical theory of deformations for fixing these problems in elastic vicinity, as the simplest.

Using generalised finite strain measures, Borah /9/ has used the notion of the transition principle. Many researchers /10-24/ have carried out the transition principle to solve the problems associated with extraordinary sorts of stable systems together with cylinders, shells and disc and many others, i.e., the stresses in circular cylinder composed of FGM are evaluated by Aggarwal et al. /11/ and determined that functionally graded material is higher in comparison to isotropic material. According to Sharma et al. /17/ analysis of creep torsion in a thick cylinder beneath the impact of pressure at the internal and external surface, composite materials are more advantageous for design.

In the current problem, thermal stresses are calculated in elastic and plastic state in transversely isotropic rotating disk constituted of functionally graded piezoelectric material subjected to inner pressure.

### GOVERNING MATHEMATICAL EQUATIONS

A thin rotating disc with radii on the inside and outside as  $r_1$  and  $r_2$ , respectively, is taken into consideration and  $\omega$ 

By using Eqs.(3), (4), (5) and (6), stresses are given as

is the angular velocity of the disk. The disk considered here is successfully in a plane stress state i.e.  $(T_{zz} = 0)$ . The displacements are taken as

$$u=r(1-\beta); v=0 \text{ and } w=dz$$
, (1)

where:  $\beta$  is a function of  $r = \sqrt{x^2 + y^2}$ ; and d is constant.

By implementing generalised strain measure, the components of strains are given by

$$e_{rr} = \frac{1}{n} [1 - (r\beta' + \beta)^{n}], \ e_{\theta\theta} = \frac{1}{n} [1 - \beta^{n}], \ e_{zz} = \frac{1}{n} \Big[ 1 - (1 - d)^{n} \Big],$$
$$e_{r\theta} = e_{\theta z} = e_{zr} = 0,$$
(2)

where: *n* is the strain measure and  $\beta' = d\beta/dr$ .

According to Hook's law

$$T_{rr} = c_{11}e_{rr} + (c_{11} - 2c_{66})e_{\theta\theta} + c_{13}e_{zz} - e_{11}E_r - \beta_1\theta,$$
  

$$T_{\theta\theta} = (c_{11} - 2c_{66})e_{rr} + c_{11}e_{\theta\theta} + c_{13}e_{zz} - e_{12}E_r - \beta_2\theta,$$
  

$$T_{zz} = T_{zr} = T_{r\theta} = T_{\theta z} = 0,$$
(3)

where:  $\beta_1 = \alpha_1 c_{11} + 2\alpha_2 c_{12}$ ;  $\beta_2 = \alpha_1 c_{12} + 2\alpha_2 (c_{22} + c_{33})$ ;  $\alpha_1$  is a coefficient of linear thermal expansion across the axis of symmetry;  $\alpha_2$  is the quantity orthogonal to axis of symmetry; and  $\theta$  is temperature given by  $\theta_0 \log(r/b)/\log(a/b)$ ;  $\theta_0$  is constant.

Electric displacement equations are given as

 $D_r = \epsilon_{11} e_{rr} + \epsilon_{12} e_{\theta\theta} + \epsilon_{13} e_{zz} + \eta_{11} E_r, \quad D_{\theta} = D_z = 0,$ (4)where:  $c_{11}$ ,  $c_{66}$ ,  $c_{13}$  are material constants;  $\in_{11}$ ,  $\in_{12}$ ,  $\in_{13}$  are piezoelectric coefficients; and  $\eta_{11}$  is dielectric constant.

From Eqs.(2) and (4) we have

$$D_r = \frac{C_1}{r} = \frac{1}{r}, \quad E_r = \frac{1}{\eta_{11}} \left[ \frac{1}{r} - \epsilon_{11} e_{rr} - \epsilon_{12} e_{\theta\theta} \right].$$
(5)

Taking variable compressibility as

Variable density and thickness are given by

$$C_{11} = C_{011} \left(\frac{r}{b}\right)^k, \ C_{12} = C_{012} \left(\frac{r}{b}\right)^k, \ C_{13} = C_{013} \left(\frac{r}{b}\right)^k,$$
$$C_{66} = C_{066} \left(\frac{r}{b}\right)^k.$$
(6)

$$T_{rr} = \frac{C_{011}}{n} \left(\frac{r}{b}\right)^{k} (1 - \beta^{n} (1 + P)^{n}) + \frac{(C_{011} - 2C_{066})}{n} \left(\frac{r}{b}\right)^{k} (1 - \beta^{n}) + \frac{C_{013}}{n} \left(\frac{r}{b}\right)^{k} (1 - (1 - d)^{n}) + \frac{\epsilon_{11}}{n\eta_{11}} \left[\epsilon_{11} (1 - \beta^{n} (1 + P)^{n}) + \epsilon_{12} (1 - \beta^{n}) - \frac{1}{r}\right] - (\alpha_{1}C_{011} + 2\alpha_{1}C_{012}) \left(\frac{r}{b}\right)^{k} \theta_{0} \frac{\log(r/b)}{\log(a/b)},$$

$$T_{\theta\theta} = \frac{(C_{011} - 2C_{066})}{n} \left(\frac{r}{b}\right)^{k} (1 - \beta^{n} (1 + P)^{n}) + \frac{C_{011}}{n} \left(\frac{r}{b}\right)^{k} (1 - \beta^{n}) + \frac{C_{013}}{n} \left(\frac{r}{b}\right)^{k} (1 - (1 - d)^{n}) + \frac{\epsilon_{12}}{n\eta_{11}} \times \left[\epsilon_{11} (1 - \beta^{n} (1 + P)^{n}) + \epsilon_{12} (1 - \beta^{n}) - \frac{1}{r}\right] - (\alpha_{1}C_{012} + \alpha_{1}(C_{022} + C_{022})) \left(\frac{r}{b}\right)^{k} \theta_{0} \frac{\log(r/b)}{\log(a/b)},$$
(7)

where:  $r\beta' = \beta P$ .

 $C (\lambda^k)$ 

The condition of equilibrium for rotating disc is given as

$$\frac{d}{dr}(hT_{rr}) + hT_{\theta\theta} + h\rho\omega^2 r = 0.$$
(8)  $\rho = \rho_0 \left(\frac{r}{h}\right)^t$ , and  $h = h_0 \left(\frac{r}{h}\right)^m$ 

Using Eqs.(7) and (9) in equations in the equilibrium Eq.(8) we have

$$\left(C_{011}\beta^{n+1} + \beta^{n+1}\left(\frac{r}{b}\right)^{-k} \frac{\epsilon_{11}^2}{\eta_{11}}\right) P(1+P)^{n-1} \frac{dP}{d\beta} = (m+k)\frac{C_{011}}{n}(1-\beta^n(1+P)^n) + (m+k)\frac{C_{011}}{n}(1-\beta^n) + \frac{C_{013}}{n}(m+k)(1-(1-d)^n) + \frac{C$$

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(9)

$$+\frac{2C_{066}}{n}(1-\beta^{n}(1+P)^{n})-(m+k+1)\frac{C_{066}}{n}(1-\beta^{n})+\left(\frac{r}{b}\right)^{-k}\left(\frac{\epsilon_{11}^{2}(m+1)}{n\eta_{11}}(1-\beta^{n}(1+P)^{n})+\frac{\epsilon_{11}\epsilon_{12}(m+1)}{n\eta_{11}}(1-\beta^{n})+\frac{\epsilon_{12}}{r\eta_{11}}-\frac{\epsilon_{12}}{r\eta_{11}}-\frac{\epsilon_{12}^{2}}{\eta_{11}}-\frac{\epsilon_{12}^{2}}{\eta_{11}}(1-\beta^{n})\right)-(\alpha_{1}C_{011}+2\alpha_{1}C_{012})\left(\frac{r}{b}\right)^{k}\theta_{0}\frac{\log(r/b)}{\log(a/b)}-(\alpha_{1}C_{012}+\alpha_{1}(C_{022}+C_{022}))\left(\frac{r}{b}\right)^{k}\times\\\times\theta_{0}\frac{\log(r/b)}{\log(a/b)}+(m+t+2)\frac{\rho_{0}\omega^{2}r^{t+1}}{b^{t}}-C_{011}\beta^{n}P(1+P)^{n}$$
(10)  
The conditions to be implemented are considered as

The conditions to be implemented are considered as  

$$T_{rr} = 0$$
 at  $r = b$ , and  $T_{rr} = -p$  at  $r = a$ . (11)

Conversion from elastic to plastic

As stated by transition theory, conversion from elastic to plastic occurs at critical point  $P \rightarrow \pm \infty$ . The transition function for evaluating the plastic stresses is taken as

$$R = T_{rr} + B + \beta_{1}\theta = \frac{C_{011}}{n} \left(\frac{r}{b}\right)^{k} (1 - \beta^{n} (1 + P)^{n}) + \frac{(C_{011} - 2C_{066})}{n} \left(\frac{r}{b}\right)^{k} (1 - \beta^{n}) + \frac{C_{013}}{n} \left(\frac{r}{b}\right)^{k} (1 - (1 - d)^{n}) + \frac{\epsilon_{11}}{n\eta_{11}} \times \left[\epsilon_{11} (1 - \beta^{n} (1 + P)^{n}) + \epsilon_{12} (1 - \beta^{n}) - \frac{1}{r}\right] + B,$$
(12)

where: *B* is any constant.

Applying logarithmic differentiation in Eq.(12) and using Eq.(10), and then using  $P \rightarrow \pm \infty$ , we get

$$R = AC_{3}r^{C_{1}}e^{C_{2}r^{-k}}, \quad c_{1} = \frac{(m-k+1)C_{011} + 2C_{066}}{\frac{e_{11}^{2}}{\eta_{11}} - C_{011}},$$
  
and 
$$c_{2} = \frac{\frac{e_{11}^{2}}{\eta_{11}}(m+1)}{\left(\frac{e_{11}^{2}}{\eta_{11}} - C_{011}\right)b^{-k}}.$$
 (13)  
we stresses evaluated using Eqs.(13) and (8), are given

Th

$$T_{rr} = AC_3 r^{C_1} e^{C_2 r} - B - \beta_1 \theta, \qquad (14)$$

$$T_{\theta\theta} = (m+1)C_3r^{C_1}e^{C_2r^{-k}} + C_3C_1r^{C_1}e^{C_2r^{-k}} - (\alpha_1C_{011} + 2\alpha_2C_{012})\left(\frac{r}{b}\right)^k \times \frac{(\alpha_1C_0)}{r\log(a/b)} + \frac{1}{r\log(a/b)} - kC_3C_2r^{C_1-k}e^{C_2r^{-k}} + \rho_0r^2\omega^2\left(\frac{r}{b}\right)^t$$
Using boundary conditions of Eq.(11) in Eq.(14) we have

$$B = \frac{-p_1 + (\alpha_1 C_{011} + 2\alpha_1 C_{012}) \left(\frac{a}{b}\right) \theta}{a^{C_1} e^{C_2 a^{-k}} - b^{C_1} e^{C_2 b^{-k}}} b^{C_1} e^{C_2 b^{-k}},$$
  

$$C_3 = \frac{-p_1 + (\alpha_1 C_{011} + 2\alpha_1 C_{012}) \left(\frac{a}{b}\right)^k \theta}{a^{C_1} e^{C_2 a^{-k}} - b^{C_1} e^{C_2 b^{-k}}}.$$
 (15)

Yielding criterion is taken as  $|T_{rr} - T_{\theta\theta}|_{r=a} =$  $-(m+1)C_3a^{C_1}e^{C_2a^{-k}} - B + (\alpha_1C_{011} + 2\alpha_2C_{012})\theta_0 \left[ \left(\frac{a}{b}\right)^{k-1-m} - \left(\frac{a}{b}\right)^k + \frac{1}{a\log(a/b)} \right] - kC_3C_2a^{C_1-k}e^{C_2a^{-k}} - \rho_0a^2\omega^2 \left(\frac{a}{b}\right)^t = \gamma_1 \cdot (16)$ =

Pressure needed for initial yielding is given by

$$p_{i} = \frac{p}{\gamma_{1}} = \frac{a^{C_{1}}e^{C_{2}a^{-k}} - b^{C_{1}}e^{C_{2}b^{-k}}}{ma^{C_{1}}e^{C_{2}b^{-k}} + b^{C_{1}}e^{C_{2}b^{-k}}} \begin{cases} 1 + \frac{(\alpha_{1}C_{011} + 2\alpha_{1}C_{012})\left(\frac{a}{b}\right)^{k}\left(ma^{C_{1}}e^{C_{2}b^{-k}} - b^{C_{1}}e^{C_{2}b^{-k}}\right)\theta_{0}}{a^{C_{1}}e^{C_{2}b^{-k}} - b^{C_{1}}e^{C_{2}b^{-k}}} + (\alpha_{1}C_{011} + 2\alpha_{1}C_{012}) \times \\ \times \left(\left(\frac{a}{b}\right)^{k-m-1} - \left(\frac{a}{b}\right)^{k} + \frac{1}{a\log(a/b)}\right)\left(\frac{a}{b}\right)^{k} + \frac{\rho_{0}a^{2}\omega^{2}}{\gamma_{1}}\left(\frac{a}{b}\right)^{t}\right). \end{cases}$$
(17)

Absolutely plastic state happens at the external surface. Consequently 
$$|T_{rr} - T_{\theta\theta}|$$
 from Eqs.(14) at  $r = b$ ,  
 $|T_{rr} - T_{\theta\theta}|_{r=b} = \left| -(m+1)C_3b^{C_1}e^{C_2b^{-k}} - B + (\alpha_1C_{011} + 2\alpha_2C_{012})\theta_0 \frac{1}{b\log(a/b)} - kC_3C_2b^{C_1-k}e^{C_2b^{-k}} - \rho_0b^2\omega^2 \right| = \gamma_2 \cdot (18)$ 
Pressure needed for absolutely plastic state is given by

$$p_{f} = \frac{p}{\gamma_{2}} = \frac{(a/b)^{C_{1}} e^{C_{2}a^{-k}} - e^{C_{2}b^{-k}}}{m(a/b)^{C_{1}} e^{C_{2}b^{-k}} + e^{C_{2}b^{-k}}} \left\{ 1 + \frac{(\alpha_{1}C_{011} + 2\alpha_{2}C_{012})(a/b)^{k} \left(ma^{C_{1}} e^{C_{2}b^{-k}} - b^{C_{1}} e^{C_{2}b^{-k}}\right) \theta_{0}}{R_{0}^{C_{1}} e^{C_{2}b^{-k}} - e^{C_{2}b^{-k}}} + (\alpha_{1}C_{011} + 2\alpha_{2}C_{012}) \times \left(a/b\right)^{k} + \frac{(\alpha_{1}C_{011} + 2\alpha_{2}C_{012})}{R_{0}^{C_{1}} e^{C_{2}b^{-k}} - e^{C_{2}b^{-k}}}\right) \theta_{0}} + (\alpha_{1}C_{011} + 2\alpha_{2}C_{012}) \times \left(a/b\right)^{k} + \frac{(\alpha_{1}C_{011} + 2\alpha_{2}C_{012})}{R_{0}^{C_{1}} e^{C_{2}b^{-k}} - e^{C_{2}b^{-k}}}\right) \theta_{0}} + (\alpha_{1}C_{011} + 2\alpha_{2}C_{012}) \times \left(a/b\right)^{k} + \frac{(\alpha_{1}C_{011} + 2\alpha_{2}C_{012})}{R_{0}^{C_{1}} e^{C_{2}b^{-k}} - e^{C_{2}b^{-k}}}\right) \theta_{0}} + (\alpha_{1}C_{011} + 2\alpha_{2}C_{012}) \times \left(a/b\right)^{k} + \frac{(\alpha_{1}C_{011} + 2\alpha_{2}C_{012})}{R_{0}^{C_{1}} e^{C_{2}b^{-k}} - e^{C_{2}b^{-k}}}\right) \theta_{0}} + (\alpha_{1}C_{011} + 2\alpha_{2}C_{012}) \times \left(a/b\right)^{k} + \frac{(\alpha_{1}C_{011} + 2\alpha_{2}C_{012})}{R_{0}^{C_{1}} e^{C_{2}b^{-k}} - e^{C_{2}b^{-k}}}\right) \theta_{0}} + (\alpha_{1}C_{011} + 2\alpha_{2}C_{012}) \times \left(a/b\right)^{k} + \frac{(\alpha_{1}C_{011} + 2\alpha_{2}C_{012})}{R_{0}^{C_{1}} e^{C_{2}b^{-k}} - e^{C_{2}b^{-k}}}\right) \theta_{0}} + (\alpha_{1}C_{011} + 2\alpha_{2}C_{012}) \times \left(a/b\right)^{k} + \frac{(\alpha_{1}C_{011} + 2\alpha_{2}C_{012})}{R_{0}^{C_{1}} e^{C_{2}b^{-k}} - e^{C_{2}b^{-k}}}\right) \theta_{0}} + (\alpha_{1}C_{011} + 2\alpha_{2}C_{012}) \times \left(a/b\right)^{k} + \frac{(\alpha_{1}C_{011} + 2\alpha_{2}C_{012})}{R_{0}^{C_{1}} e^{C_{2}b^{-k}} - e^{C_{2}b^{-k}}}\right) \theta_{0}$$

 $\frac{1}{(e_{11}^2/C_{011}\eta_{11})-1}$ ; and  $C'_2 = b^k (m+1)$ .

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STRUCTURAL INTEGRITY AND LIFE Vol. 23, No.2 (2023), pp. 205-212 Components assumed in non-dimensional form are as follows

$$R = \frac{r}{b}, \quad R_0 = \frac{a}{b}, \quad \sigma_r = \frac{T_{rr}}{\gamma_1}, \quad \sigma_\theta = \frac{T_{\theta\theta}}{\gamma_1}, \quad p_i = \frac{p}{\gamma_1}, \quad p_f = \frac{p}{\gamma_2}, \quad \Omega_1 = \frac{\rho_0 b^2 \omega^2}{\gamma_1}, \quad \Omega_2 = \frac{\rho_0 b^2 \omega^2}{\gamma_2}. \tag{20}$$

Using Eqs.(14) and (20), stresses in non-dimensional form are

$$\sigma_{r} = \frac{T_{rr}}{\gamma_{1}} = (\alpha_{1}C_{011} + 2\alpha_{1}C_{012})(R)^{k} \frac{\theta \log(R_{0})}{\log(R)} - \frac{-p_{i} + (\alpha_{1}C_{011} + 2\alpha_{2}C_{012})(R_{0})^{k} \theta}{a^{C_{1}}e^{C_{2}(R_{0}b)^{-k}} - b^{C_{1}}e^{C_{2}b^{-k}}} e^{C_{2}b^{-k}},$$

$$\sigma_{\theta} = \frac{T_{\theta\theta}}{\gamma_{1}} = \frac{(m+1+C_{1}-kC_{2}b^{-k}R^{-k})e^{C_{2}b^{-k}}(bR)^{C_{1}}(-p_{i} + (\alpha_{1}C_{011} + 2\alpha_{2}C_{012}))(R_{0})^{k}\theta}{(R_{0}^{C_{1}}e^{C_{2}(R_{0}b)-k} - e^{C_{2}b^{-k}})} \times \left[ \frac{(m+k+1)(R)^{k} \frac{\theta \log(R)}{\log(R_{0})} + (R)^{k} \frac{\theta}{\log(R_{0})}}{\log(R_{0})} \right] + (R)^{t+2}\Omega_{1}.$$
(21)

Pressure needed for initial yielding in non - dimensional form is given by

$$p_{i} = \frac{p}{\gamma_{1}} = \frac{a^{C_{1}}e^{C_{2}R_{0}^{-k}b^{-k}} - b^{C_{1}}e^{C_{2}b^{-k}}}{ma^{C_{1}}e^{C_{2}b^{-k}} + b^{C_{1}}e^{C_{2}b^{-k}}} \left\{ \times 1 + \frac{(\alpha_{1}C_{011} + 2\alpha_{1}C_{012})(R_{0})^{k}(mR_{0}^{C_{1}}e^{C_{2}b^{-k}} - e^{C_{2}b^{-k}})\theta_{0}}{R_{0}^{C_{1}}e^{C_{2}b^{-k}} - e^{C_{2}b^{-k}}} + (\alpha_{1}C_{011} + 2\alpha_{1}C_{012}) \times \left( (R_{0})^{k-m-1} - (R_{0})^{k} + \frac{1}{bR_{0}\log(R_{0})} \right)(R_{0})^{k} + \Omega_{2}(R_{0})^{t} \right\},$$

$$(22)$$

$$e_{11}^{2}(m+1)$$

where:  $C_1 = \frac{(m-k+1)+2C_{011}/C_{066}}{(e_{11}^2/C_{011}\eta_{11})-1}$ ; and  $C_2 = \frac{\frac{11}{\eta_{11}}(m+1)}{\left(\frac{e_{11}^2}{\eta_{11}}-C_{011}\right)b^{-k}}$ .

Pressure required for fully plastic in non - dimensional form is given by

$$p_{f} = \frac{p}{\gamma_{2}} = \frac{a^{C_{1}}e^{C_{2}}R_{0}^{-k}b^{-k}}{ma^{C_{1}}e^{C_{2}b^{-k}} + b^{C_{1}}e^{C_{2}b^{-k}}} \left\{ 1 + \frac{(\alpha_{1}C_{011} + 2\alpha_{1}C_{012})(R_{0})^{k}(mR_{0}^{C_{1}}e^{C_{2}b^{-k}} - e^{C_{2}b^{-k}})\theta_{0}}{R_{0}^{C_{1}}e^{C_{2}b^{-k}} - e^{C_{2}b^{-k}}} + (\alpha_{1}C_{011} + 2\alpha_{1}C_{012}) \times \left( (R_{0})^{k-m-1} - (R_{0})^{k} + \frac{1}{bR_{0}\log(R_{0})} \right)(R_{0})^{k} + \Omega_{2}(R_{0})^{t} \right\},$$

$$(23)$$

where:  $C'_1 = \frac{m - k + 1}{(e_{11}^2 / C_{011} \eta_{11}) - 1}$ ; and  $C'_2 = b^k (m + 1)$ .

Fully plastic stresses in non-dimensional form are given by

$$\sigma_{r} = \frac{T_{rr}}{\gamma_{1}} = (\alpha_{1}C_{011} + 2\alpha_{1}C_{012})(R)^{k} \frac{\theta \log(R_{0})}{\log(R)} - \frac{-p_{i} + (\alpha_{1}C_{011} + 2\alpha_{2}C_{012})(R_{0})^{k}\theta}{a^{C_{1}'}e^{C_{2}'(R_{0}b)^{-k}} - b^{C_{1}'}e^{C_{2}'b^{-k}}} e^{C_{2}'b^{-k}},$$

$$\sigma_{\theta} = \frac{T_{\theta\theta}}{\gamma_{1}} = \frac{(m+1+C_{1}'-kC_{2}'b^{-k}R^{-k})e^{C_{2}'b^{-k}}(bR)^{C_{1}'}(-p_{i} + (\alpha_{1}C_{011} + 2\alpha_{2}C_{012}))(R_{0})^{k}\theta}{(R_{0}^{C_{1}'}e^{C_{2}(R_{0}b)^{-k}} - e^{C_{2}'b^{-k}})} \times \left[ (m+k+1)(R)^{k} \frac{\theta \log(R)}{\log(R_{0})} + (R)^{k} \frac{\theta}{\log(R_{0})} \right] + (R)^{t+2}\Omega_{1},$$
(24)
where:  $C_{1}' = \frac{m-k+1}{2}$  and  $C_{1}' = \frac{b^{k}(m+1)}{2}$ 

where:  $C'_1 = \frac{m-k+1}{(e_{11}^2 / C_{011} \eta_{11}) - 1}$ ; and  $C'_2 = b^k (m+1)$ .

## NUMERICAL CALCULATIONS AND DISCUSSION

# PZT4 and BaTiO3

Figures 1a and 1b illustrate pressure values on innermost surface of the transversely isotropic disc made of barium titanate (BaTiO<sub>3</sub>) and PZT4 (piezoceramic) with thickness parameter t = 1, variable density parameter m = 1, temperature  $\theta = 5$ , and angular velocity of 100 and 500, respectively. It may be observed that pressure value increases with increasing radii ratio up to the centre of the disk and it is further decreased with increasing value of radii ratio for k = 1, 2, and 3, in case of both materials. Pressure value is maximal for k = 3. With the increasing value of thermal

gradient  $\theta = 10$ , the pressure value increases as illustrated in Figs. 2a and 2b. Internal pressure is higher for the transversely isotropic disk made of PZT4.



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Figure 2. Internal pressure on BaTiO<sub>3</sub> and PZT4 with t = 1, m = 1,  $\theta = 10$ , and angular velocity of a) 100; and b) 500.

Figures 3a and 3b show the plot of internal pressure with radii ratios for circular disk made of BaTiO<sub>3</sub> and PZT4 with thickness parameter t = 2, variable density parameter m = 2, temperature  $\theta = 5$ , and angular velocity of 100 and 500, in respect. Pressure has minimal value at the innermost surface of the disk and maximal value at the outermost surface for k = 1, 2, and 3. Pressure values are further increasing with increasing value of temperature gradient ( $\theta = 10$ ), as illustrated in Figs. 4a and 4b. Internal pressure is higher for the transversely isotropic disk made of PZT4.







Figure 4. Internal pressure on BaTiO<sub>3</sub> and PZT4 with t = 2, m = 2,  $\theta = 10$ , and angular velocity of a) 100; and b) 500.

Figures 5a and 5b demonstrate plots of pressure values in absolutely plastic state for the transversely isotropic disk of BaTiO<sub>3</sub> and PZT4 with thickness parameter t = 1, variable density parameter m = 1, temperature  $\theta = 5$ , and angular velocity of 100 and 500, respectively. Pressure in absolutely plastic state achieves its maximal value at the centre of the disk for k = 1, 2, and 3. Pressure values are further increasing with increasing value of temperature gradient ( $\theta = 10$ ) as illustrated in Figs. 6a and 6b. Pressure in absolutely plastic state is higher for the transversely isotropic disk of PZT4.









Figure 6. Fully plastic pressure of BaTiO<sub>3</sub> and PZT4 with t = 1, m = 1,  $\theta = 10$ , and angular velocity of a) 100; and b) 500.

Figures 7a and 7b show plots of pressure values in fully plastic state for transversely isotropic disk of BaTiO<sub>3</sub> and PZT4 with thickness parameter t = 2, variable density parameter m = 2, temperature  $\theta = 5$ , and angular velocity of 100 and 500, in respect. Pressure in fully plastic state achieves its maximal value at the outermost surface of the disk for k = 1, 2, and 3. Pressure values are getting larger with the increment in temperature gradient ( $\theta = 10$ ) as illustrated in Figs. 8a and 8b. Pressure in absolutely plastic state is higher for the transversely isotropic disc of PZT4.



Figure 8. Fully plastic pressure of BaTiO<sub>3</sub> and PZT4 with t = 2, m = 2,  $\theta = 10$ , and angular velocity of a) 100; and b) 500.

#### Transitional stresses

Figures 9a and 9b show the plot of transitional stresses with radii ratios for the transversely isotropic disk of BaTiO<sub>3</sub> and PZT4 with thickness parameter t = 1, variable density parameter m = 1, temperature  $\theta = 5$ , and angular velocity of 100 and 500, respectively. It may be noted that transitional stresses are tensile in nature and increasing with radii ratio and achieve their maximum at outermost surface of the diskc for k = 1, 2, and 3, in case of both materials. With the increasing value of thermal gradient  $\theta = 10$ , the values of transitional stresses increase as illustrated in Figs. 10a and 10b. Transitional stresses are higher for transversely isotropic disc made of PZT4.





Figures 11a and 11b show plots of transitional stresses with radii ratios for circular disk of BaTiO<sub>3</sub> and PZT4 with thickness parameter t = 2, variable density parameter m = 2, temperature  $\theta = 5$ , and angular velocity of 100 and 500, in respect. Transitional stresses have maximal value at the outer surface of the disk for k = 1, 2, and 3. With increasing value of thermal gradient  $\theta = 10$ , the value of transitional stresses increases as illustrated in Figs. 12a and 12b. Transitional

INTEGRITET I VEK KONSTRUKCIJA Vol. 23, br.2 (2023), str. 205–212 stresses are higher for the transversely isotropic disk made of PZT4.



Figure 11. Transitional stresses for BaTiO<sub>3</sub> and PZT4 with t = 2, m = 2,  $\theta = 5$ , and angular velocity of a) 100; and b) 500.



Figure 12. Transitional stresses for BaTiO<sub>3</sub> and PZT4 with t = 2, m = 2,  $\theta = 10$ , and angular velocity of a) 100; and b) 500.

#### Fully plastic stresses

Figures 13a and 13b show plots of absolutely plastic stresses with radii ratios for circular disk of BaTiO<sub>3</sub> and PZT4 with thickness parameter t = 1, variable density parameter m = 1, temperature  $\theta = 5$ , and angular velocity of 100 and 500, respectively. Transitional stresses are tensile in nature and increasing with radii ratio and achieve largest value at the outermost surface of the disk for k = 1, 2, and 3. With the increasing value of thermal gradient  $\theta = 10$ , the value of transitional stresses are higher for transversely isotropic disc made of PZT4.

Figures 15a and 15b show plots of fully plastic stresses with radii ratios for circular disk of BaTiO<sub>3</sub> and PZT4 with thickness parameter t = 2, variable density parameter m = 2, temperature  $\theta = 5$ , and angular velocity of 100 and 500, in respect. Transitional stresses are tensile in nature and increasing with radii ratio and achieve the largest value at the outermost surface of the disk for k = 1, 2, and 3. With the increasing value of thermal gradient  $\theta = 10$ , the value of transitional stresses increases as illustrated in Figs. 16a and 16b. Fully plastic stresses are higher for the transversely isotropic disc made of PZT4.







Figure 14. Fully plastic stresses for BaTiO<sub>3</sub> and PZT4 with t = 1, m = 1,  $\theta = 10$ , and angular velocity of a) 100; and b) 500.



Figure 15. Fully plastic stresses for BaTiO<sub>3</sub> and PZT4 with t = 2, m = 2,  $\theta = 5$ , and angular velocity of a) 100; and b) 500.

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# CONCLUSION

Studied here is the deformation in a thin circular disk made of BaTiO<sub>3</sub> and PZT4, due to angular velocity, temperature and pressure. In the present research, the components of transitional stresses are obtained and shown graphically to depict the effects of rotation, pressure, and temperature. There is significant impact of rotation and temperature on stresses for transversely isotropic rotating disk made of barium titanate (BaTiO<sub>3</sub>) and PZT4 (piezoceramic). With increase in rotation and temperature, the circumferential stresses further increase significantly. It is concluded on the basis of all the calculations and results that the disk of piezoelectric material BaTiO<sub>3</sub> is better than the disk made of piezoceramic material PZT4. Parameters obtained from this research can be used to design pressure sensors, radar antennae, and many other devices, also machines, or structures, in engineering applications.

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